# H. AIRAULT P. MALLIAVIN Some heat operators on $\mathbb{P}(\mathbb{R}^d)$

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### SOME HEAT OPERATORS ON $\mathbb{P}(\mathbb{R}^d)$

#### **H.AIRAULT AND P.MALLIAVIN**

ABSTRACT. To a diffusion on  $\mathbb{R}^n$ , we associate a heat equation on the path space  $P(\mathbb{R}^n)$  of continuous maps defined on [0, 1] with values in  $\mathbb{R}^n$ . The heat operator is obtained by taking the sum of the square of twisted derivatives with respect to an orthonormal basis of the Cameron-Martin space. We give the expression of this heat operator when it acts on cylindrical functions defined on the Wiener space.

RÉSUMÉ. A une diffusion sur  $\mathbb{R}^n$ , on associe une équation de la chaleur sur  $P(\mathbb{R}^n)$ , l'espace des applications continues, définies sur [0,1] à valeurs dans  $\mathbb{R}^n$ . L'opérateur de la chaleur est construit en prenant la somme des carrés des dérivées amorties par rapport à une base de l'espace de Cameron-Martin. On exprime cet opérateur de la chaleur sur les fonctions cylindriques définies sur l'espace de Wiener.

#### **§0:** INTRODUCTION

Let  $\Omega = P(\mathbb{R}^n)$  be the Wiener space of continuous maps from [0,1] with values in  $\mathbb{R}^n$ and let  $I: \omega \to x(\omega)$  be a map from  $\Omega$  to itself. We assume that, for any  $\tau \in [0,1]$ , the map  $\omega \to x_\tau(\omega)$  is differentiable on the Wiener space and that it is adapted. Given the heat operator A on the Wiener space  $P(\mathbb{R}^n)$  [See [2]], we construct a new operator  $\tilde{A}$ . The operator  $\tilde{A}$  is the image of the operator A through the map I, and satisfy the identity

$$A(foI) = (\hat{A}f)oI \tag{0.1}$$

This allows to obtain a heat equation associated to the map I. The operator A is obtained by taking the sum of the square of twisted derivatives with respect to a basis  $(e_{k,\alpha})_{k\geq 0, 1\leq \alpha\leq n}$  of the Cameron-Martin space of the Wiener space. We express the operator  $\tilde{A}$  when it is applied to cylindrical functions defined on the Wiener space  $P(\mathbb{R}^n)$ . The identity (0.1) extends to the Wiener space the elementary following computation: Let  $A = \frac{d^2}{dx^2}$  be the derivative of order 2 on  $\mathbb{R}$ , viewed as the infinitesimal generator of the brownian diffusion on  $\mathbb{R}$ , and let  $\phi$  be a differentiable homeomorphism of  $\mathbb{R}$ ; then  $A(fo\phi) = (\tilde{A}f)o\phi$  holds where

$$\tilde{A} = (\phi'[\phi^{-1}(x)])^2 \frac{d^2}{dx^2} + \phi''(\phi^{-1}(x)) \frac{d}{dx}$$
(0.2)

is the infinitesimal generator of a new diffusion on R. We explicit the computations when the map I is the Ito map associated to the diffusion on  $R^n$ 

$$dx(\tau) = d\omega(\tau) + b(x(\tau))d\tau \tag{0.3}$$

This method extends when I is a map from  $P(\mathbb{R}^n)$  to P(M) the path space of a Riemannian manifold M; it allows to obtain new diffusions on the space P(M). See [3] for further developments related to this subject.

#### **§1** NOTATIONS AND DEFINITIONS

Let  $\omega$  be the brownian on  $\mathbb{R}^n$ , and consider the diffusion given by the stochastic differential equation (0.3) where b is a differentiable map from  $\mathbb{R}^n$  to  $\mathbb{R}^n$ . We denote by

$$I: \omega \to x(\omega) \tag{1.1}$$

the Ito map and let

 $g_t: \omega \to \sqrt{t}\omega \tag{1.2}$ 

be the dilation on  $P(\mathbb{R}^n)$ . The evaluation map  $\varphi_{\tau}$  at  $\tau$  is given by

φ

$$\sigma_{\tau}(\omega) = \omega_{\tau}$$

and we put

$$\tilde{\varphi}_{\tau} = \varphi_{\tau} o I \tag{1.3}$$

We denote by  $\mu$  the Wiener measure on  $\Omega = C([0,1], \mathbb{R}^n)$  and let  $\nu_t = (Iog_t) * \mu$  be the image of the Wiener measure  $\mu$  by the map  $Iog_t$ . The Cameron-Martin space H is the set of differentiable functions h in  $L^2([0,1];\mathbb{R})$  such that  $\int_0^1 h'(s)^2 ds < +\infty$ . We consider for a basis of the Cameron-Martin space H, the functions defined by

$$e_{k,\alpha}(\tau) = \sqrt{2} \frac{\sin(k\pi\tau)}{k\pi} \otimes \epsilon_{\alpha}$$
(1.4)

with  $k \geq 1$  and

$$e_{0,\alpha}(\tau)=\tau\otimes\varepsilon_{\alpha}$$

where  $(\varepsilon_{\alpha})_{\alpha=1,\ldots,n}$  is a basis of  $\mathbb{R}^n$ . We shall write

$$e_k(\tau) = \sqrt{2} rac{\sin(k\pi\tau)}{k\pi}$$
  
 $e_0(\tau) = \tau$ 

Let h be an element of the Cameron-Martin space H and let  $f: \Omega \to \mathbb{R}^n$ . We let

$$D_h f(\omega) = \frac{d}{d\varepsilon}\Big|_{\varepsilon=0} f(\omega + \varepsilon h)$$
(1.5)

For  $s \in [0, 1]$ , we define  $D_s f(\omega)$  such that

$$D_h f(\omega) = \int_0^1 D_s f(\omega) h'(s) ds$$
 (1.6)

Let

$$\nabla f(\omega)(s) = \int_0^s D_u f(\omega) du \tag{1.7}$$

On the Cameron-Martin space H, denote  $(|)_H$  the scalar product given by  $(h_1|h_2)_H = \int_0^1 h'_1(s)h'_2(s)ds$ . We have

$$D_{h}(\omega) = (h|\nabla f(\omega)) \tag{1.8}$$

and for  $f_1$  and  $f_2$  defined on  $\Omega$  with real values, we have

$$(\nabla f_1(\omega)|\nabla f_2(\omega)) = \int_0^1 D_s f_1(\omega) D_s f_2(\omega) ds$$
(1.9)

#### §2 TWISTING AND INTERTWINNING IDENTITIES

Let b' be the Jacobian map of b and let h in the Cameron-Martin space; we put

$$\beta(\tau)(\omega) = \int_0^\tau exp[\int_s^\tau b'(\omega_u)du]h'(s)ds \qquad (2.1)$$

**Definition 2.1.** We call  $\beta(\tau)$  the twisted vector field associated to the element h through the diffusion (0.3).

We denote  $\beta'(\tau) = \frac{d}{d\tau}\beta(\tau)$  the derivative of  $\beta$  as a function of  $\tau$ . By (2.1), we have

$$\beta'(\tau)(\omega) = h'(\tau) + b'(\omega_{\tau})\beta(\tau)(\omega)$$
(2.2)

and

$$\beta(0)(\omega) = 0$$

**Lemma 2.1.** Assume that  $\beta$  and h are related by (2.1), then the derivative of the evaluation map (1.3) is

$$D_h \tilde{\varphi}_\tau(\omega) = \beta(\tau)(I\omega) \tag{2.3}$$

proof. Let  $h \in H$ ; from (1.2) and (0.3), the function

$$y^{\epsilon}(\tau)(\omega) = \tilde{\varphi}_{\tau}(\omega + \epsilon h)$$

is solution of the stochastic equation

$$dy^{\epsilon}(\tau)(\omega) = d\omega(\tau) + \epsilon h'(\tau)d\tau + b(y^{\epsilon}(\tau)(\omega))d\tau$$
(2.4)

Taking the derivative with respect to  $\epsilon$ , we obtain that

$$z(\tau)(\omega) = rac{d}{d\epsilon}_{|\epsilon=0} y^{\epsilon}(\tau)(\omega)$$

satisfies

$$dz(\tau)(\omega) = h'(\tau)d\tau + b'(x(\tau)(\omega))z(\tau)d\tau$$

and

$$z(0)(\omega)=0$$

By (2.2), we obtain the identity (2.3).

Corollary. We have

$$D_{s}x(\tau)(\omega) = exp[\int_{s}^{\tau} b'(x(u)(\omega))]du \qquad (2.5)$$

proof.  $D_s x(\tau)(\omega)$  means  $D_s \tilde{\varphi}_{\tau}(\omega)$  Thus, by (2.3) and (1.6), we have

$$\beta(\tau)(I\omega) = \int_0^\tau D_s x_\tau(\omega) h'(s) ds \qquad (2.6)$$

Then, we use (2.1).

Remark: If we denote  $\varphi_{\tau}(\omega) = \omega_{\tau}$  then (2.6) can be written

$$\beta(\tau)(\omega) = ((\nabla(\varphi_{\tau}oI)(I^{-1}(\omega)|h)_H)$$
(2.7)

Definition 2.2. We let

$$D_{\beta}f(\omega) = \frac{d}{d\varepsilon}|_{\varepsilon=0} f(\omega + \varepsilon\beta(\omega))$$
(2.8)

**Lemma 2.2.** If  $\beta$  is the twisted vector field related to h through (2.1), the following intertwinning relation holds

$$D_h(foI)(\omega) = (D_\beta f)(I\omega)$$
(2.9)

proof.

$$D_{h}(foI)(\omega) = \frac{d}{d\varepsilon}|_{\varepsilon=0}(foI)(\omega+\varepsilon h)$$
(2.10)

We verify (2.9) when  $f = \psi o \varphi_{\tau}$  where  $\varphi_{\tau}(\omega) = \omega_{\tau}$  and  $\psi : \mathbb{R}^n \to \mathbb{R}$ . For the solution  $y^{\epsilon}(\tau)$  of (2.4), we have

$$(foI)(\omega + \epsilon h) = \psi(y^{\epsilon}(\tau))$$
(2.11)

We deduce that

$$\frac{d}{d\varepsilon} \psi(y^{\epsilon}(\tau)) = \psi'(x_{\tau})\beta(\tau)(I\omega)$$
(2.12)

On the other hand

$$(D_{\beta}f)(\omega) = \psi'(\omega(\tau))\beta(\tau)(\omega)$$
(2.13)

By comparison of (2.13) and (2.12), we get (2.9).

Remark that (2.3) is the particular case of (2.9) when  $f = \varphi_{\tau}$ .

**Definition 2.3.** When h and  $\beta$  are related through (2.1), we define the twisted derivative  $\tilde{D}_h f$  by

$$D_h f(\omega) = D_\beta f(\omega) \tag{2.14}$$

Lemma 2.3. We have

$$(\tilde{D}_h^2 f)(I\omega) = D_h^2(foI)(\omega)$$
(2.15)

proof. From (2.14) and (2.9), we get

$$(D_h f)(I\omega) = D_h(foI)(\omega)$$
(2.16)

and

$$\begin{split} \ddot{D}_h(\ddot{D}_h f)(I\omega) &= D_h((\ddot{D}_h f)oI)(\omega) \\ &= D_h(D_h(foI))(\omega) \end{split}$$

Thus, we obtain (2.15).

#### H.AIRAULT AND P.MALLIAVIN

### §3 HEAT OPERATORS ON THE SPACE $P(\mathbb{R}^n)$

We shall construct the heat operator on  $P(\mathbb{R}^n)$  using the Ito map.

**Definition 3.1.** Let  $e_{k,\alpha}$  given by (1.4) and let  $D_{e_{k,\alpha}}$  the derivation in the direction  $e_{k,\alpha}$  (See (1.5)), we define the second order operator

$$A = \sum_{k \ge 0} \sum_{1 \le \alpha \le n} D^2_{\epsilon_{k,\alpha}}$$
(3.1)

The operator A on  $P(\mathbb{R}^n)$  does not depend on the basis of the Cameron-Martin space; See [2].

**Definition 3.2.** Let  $\tilde{D}_{e_{k,\alpha}}$  be the twisted derivation, we define the twisted operator  $\tilde{A}$  by

$$\tilde{A} = \sum_{k \ge 0} \sum_{1 \le \alpha \le n} \tilde{D}_{e_{k,\alpha}}^2$$
(3.2)

We verify that the definition (3.2) for the operator  $\tilde{A}$  on  $P(\mathbb{R}^n)$  does not depend on the basis of the Cameron-Martin space.

Lemma 3.1. We have

$$A(foI) = (\tilde{A}f)oI \tag{3.3}$$

proof. This is a consequence of (2.15), (3.1) and (3.2).

We shall see in §4 that  $\tilde{A}$  corresponds to a change of variables on the Wiener space analoguous to the elementary one (0.2) on R.

**Definition 3.3.** We denote by  $\mu$  the Wiener measure on  $\Omega = C([0,1], \mathbb{R}^n)$  and let

$$\nu_t = (Iog_t) * \mu \tag{3.4}$$

the image of the Wiener measure  $\mu$  through the map  $Iog_t$ . See (1.2).

**Theorem 3.1.** Let f be a regular function from  $P(\mathbb{R}^n)$  to R. We have

$$\frac{\partial}{\partial t} \int f(\omega) d\nu_t(\omega) = \int \tilde{A} f(\omega) d\nu_t(\omega)$$
(3.5)

proof. We verify (3.4) when  $f(\omega) = \psi(\omega_{\tau_1}, \omega_{\tau_2})$  and  $\psi: \mathbb{R}^n \to \mathbb{R}$ . In this case, we have

$$\int f(\omega)d\nu_t(\omega) = \int f(Iog_t(\omega))d\mu(\omega)$$
$$= \int \psi(x_{\tau_1}(\sqrt{t}\omega), x_{\tau_2}(\sqrt{t}\omega))d\mu(\omega)$$

From the heat equation related to the brownian motion on  $P(\mathbb{R}^n)$ , we know (see [2]) that

$$\frac{\partial}{\partial t} \int (foI)(g_t(\omega))d\mu(\omega) = \int A(foI)(g_t(\omega))d\mu(\omega)$$
(3.6)

From (3.6) and (3.3), we deduce (3.5).

# §4 EXPRESSION OF THE TWISTED LAPLACIAN $\tilde{A}$ ON CYLINDRICAL FUNCTIONS Notation. Let $p_i : \mathbb{R}^n \to \mathbb{R}$ be the projection on the *i* component; we denote

$$x^{i}(\tau) = p_{i} o \tilde{\varphi}_{\tau}$$

and  $x(\tau) = (x^1(\tau), x^2(\tau), ..., x^n(\tau))$ . We put  $\nabla x^i(\tau) = \nabla (p_i \alpha \tilde{\varphi}_{\tau})$ .

From (1.9), we have

$$(\nabla x^{i}(\tau)|\nabla x^{j}(\tau))_{H} = \int_{0}^{\tau} D_{s} x^{i}(\tau) D_{s} x^{j}(\tau) ds \qquad (4.1)$$

**Theorem 4.1.** Let  $\psi : \mathbb{R}^n \to \mathbb{R}$  and  $\varphi_{\tau}(\omega) = \omega_{\tau}$ . We have

$$\tilde{A}(\psi o \varphi_{\tau}) = \sum_{1 \le i \le n} \sum_{1 \le j \le n} (\nabla x^{i}(\tau) | \nabla x^{j}(\tau))_{H} (I^{-1} \omega) \frac{\partial^{2} \psi}{\partial x_{i} \partial x_{j}} (\omega_{\tau}) + A(x^{i}(\tau)) (I^{-1} \omega) \frac{\partial \psi}{\partial x_{i}} (\omega_{\tau})$$

$$(4.2)$$

The proof of (4.2) will result from the following lemmas and definitions.

Remark: If we take a  $\Phi = (\Phi_1, \Phi_2, ..., \Phi_n)$  to be a differentiable homeomorphism of  $\mathbb{R}^n$ and let

$$\Delta = \sum_{1 \le i \le n} \frac{\partial^2}{\partial x_i^2}$$

to be the usual Laplacian on  $\mathbb{R}^n$ , we have, for  $F:\mathbb{R}^n\to\mathbb{R}$ 

$$\Delta(Fo\Phi)=( ilde{\Delta}F)o\Phi$$

with

$$\tilde{\Delta} = \sum_{i,j} (\nabla \Phi_i | \nabla \Phi_j) (\Phi^{-1}(x)) \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{1 \le i \le n} (\Delta \Phi_i) (\Phi^{-1}(x)) \frac{\partial}{\partial x_i}$$

The theorem 4.1 is an extension of this remark to the Wiener space.

# **Definition 4.1.** Let

$$M(s,\tau)(\omega) = \exp\left[\int_{s}^{\tau} b'(\omega_{u})du\right]$$
(4.3)

From (2.5), we see that

$$M(s,\tau)(I\omega) = D_s x(\tau)(\omega) \tag{4.4}$$

**Lemma 4.2.** We assume that we have a one dimensional diffusion, i.e. n = 1 in (0.3). For  $k \ge 1$ , let

$$\beta_k(\tau)(\omega) = \int_0^\tau M(s,\tau)(\omega)\sqrt{2}\cos(k\pi s)ds \qquad (4.5)$$

and

$$\beta_o(\tau)(\omega) = \int_0^\tau M(s,\tau)(\omega) ds \tag{4.6}$$

We have

$$\sum_{k\geq 0} \beta_k(\tau)^2(\omega) = \int_0^\tau \exp[2\int_s^\tau b'(\omega_u)du]ds$$
(4.7)

proof. For fixed  $\tau$ , let g be the even function which is periodic, of period 2 and given by

$$g(s) = 1_{s \le \tau} \exp\left[\int_{s}^{\tau} b'(\omega_{u}) du\right]$$
(4.8)

Its development in Fourier series, for  $s \leq \tau$  is equal to

$$\beta_o(\tau) + \sum_{k \ge 1} 2\beta_k(\tau) \cos(k\pi s) = g(s) \tag{4.9}$$

From Parseval's identities, we obtain

$$2\int_0^1 g(s)^2 ds = 2\sum_{k\ge 0}\beta_k(\tau)^2 \tag{4.10}$$

This proves (4.7).

**Lemma 4.3.** The line vectors of the matrix  $M(s,\tau)(I\omega)$  are the vectors  $D_s x^i(\tau)(\omega)$ . See (4.4). For n = 1, we get

$$\sum_{k\geq 0} \beta_k(\tau)^2 (I\omega) = |\nabla x(\tau)(\omega)|_H^2$$
(4.11)

proof.

By (3.1), we have

$$D_h \tilde{\varphi}_\tau(\omega) = \int_0^\tau \exp[\int_s^\tau b'(x_u) du] h'(s) ds$$
(4.12)

thus, from (2.5), we get

$$D_{s}\tilde{\varphi}_{\tau}(\omega) = \exp[\int_{s}^{\tau} b'(x_{u})du]\mathbf{1}_{s\leq\tau}$$
(4.13)

This proves the first assertion. Then, we deduce (4.11) from (4.7) and (1.9).

**Proposition 4.4.** The second order term in  $\tilde{A}(\psi o \varphi_{\tau})$  is given by

$$(\nabla x^{i}(\tau)|\nabla x^{j}(\tau))_{H}(I^{-1}\omega)\frac{\partial^{2}\varphi}{\partial x_{i}\partial x_{j}}(\omega_{\tau})$$
(4.14)

proof. We have to calculate  $D^2_\beta(\psi o \varphi_\tau)$ , taking care that

$$\beta(\tau)(\omega) = \int_0^\tau exp[\int_s^\tau b'(\omega_u)du]h'(s)ds$$

depends on  $\omega$  when the gradient of b is not constant. We have

$$D_{\beta}(\psi \alpha \varphi_{\tau})(\omega) = \psi'(\omega_{\tau})\beta(\tau)(\omega)$$
(4.15)

and

$$D_{\beta}^{2}(\psi \phi \varphi_{\tau})(\omega) = \psi''(\omega_{\tau})[\beta(\tau)(\omega), \beta(\tau)(\omega)] + \psi'(\omega_{\tau})D_{\beta}[\beta(\tau)(\omega)]$$
(4.16)

We obtain (4.14) from (4.11), (4.16) and (3.2) as follows: Let

$$\beta_{k,\alpha}(\tau)(\omega) = \int_0^\tau exp[\int_s^\tau b'(\omega_u)du]e'_{k,\alpha}(s)ds$$
$$= \int_0^\tau e'_k(s)\exp[\int_s^\tau b'(\omega_u)du](\epsilon_\alpha)ds$$
$$= \int_0^\tau e'_k(s)M(s,\tau)(\epsilon_\alpha)ds$$

See (4.3). We put

$$M(s, au)(\epsilon_{lpha}) = \sum_{j} A^{j}_{lpha}(s, au)(\epsilon_{j})$$

We obtain

$$\beta_{k,\alpha}(\tau)(\omega) = \sum_{1 \le j \le n} \int_0^\tau e'_k(s) A^j_\alpha(s,\tau) ds(\epsilon_j)$$

We denote

$${}_{k}B^{j}_{\alpha}(\tau) = \int_{0}^{\tau} e'_{k}(s)A^{j}_{\alpha}(s,\tau)ds \qquad (4.17)$$

We have

$$\sum_{\alpha=1}^{n} \psi''(\omega_{\tau})[\beta_{k,\alpha}(\tau)(\omega),\beta_{k,\alpha}(\tau)(\omega)]$$
$$= \sum_{\alpha=1}^{n} \sum_{j_1=1,j_2=1}^{n} [{}_{k}B^{j_1}_{\alpha}(\tau)_{k}B^{j_2}_{\alpha}(\tau)]\psi''(\omega_{\tau})(\epsilon_{j_1},\epsilon_{j_2})$$

ı

$$=\sum_{j_1,j_2} \sum_{\alpha=1}^n [{}_k B^{j_1}_{\alpha}(\tau)_k B^{j_2}_{\alpha}(\tau)] \frac{\partial^2 \psi}{\partial x_{j_1} \partial x_{j_2}}(\omega_{\tau})$$

On the other hand,

$$(\nabla x^{j_1}(\tau) | \nabla x^{j_2}(\tau))_H = \sum_{\alpha=1}^n \sum_{k \ge 0} [{}_k B^{j_1}_{\alpha}(\tau)_k B^{j_2}_{\alpha}(\tau)]$$

This proves (4.14).

We shall now evaluate the first order term on cylindrical functions.

Lemma 4.5. Let  $\beta_k(\tau)(\omega)$  and  $\beta_o(\tau)(\omega)$  given by (4.5)-(4.6) and n = 1, we have

$$\sum_{k\geq 0} D_{\beta_k}[\beta_k(\tau)(\omega)] = \int_0^\tau M(s,\tau) \int_s^\tau M(s,\alpha) b''(\omega_\alpha) d\alpha$$
(4.18)

proof. By (2.2), we have

$$\beta(\tau)(\omega + \varepsilon\beta(\omega)) = \int_0^\tau exp[\int_s^\tau b'(\omega_u + \varepsilon\beta(u)(\omega))du]h'(s)ds$$
(4.19)

We deduce

$$\frac{d}{d\varepsilon} |_{\varepsilon=0} \beta(\tau)(\omega + \varepsilon \beta(\omega))$$

$$= \int_0^\tau M(s,\tau)(\omega) \int_s^\tau b''(\omega_\alpha) \beta(\alpha)(\omega) h'(s) d\alpha ds$$

$$= \int_0^\tau M(s,\tau)(\omega) \int_s^\tau b''(\omega_\alpha) \int_0^\alpha M(u,\alpha) h'(u) h'(s) du ds$$

$$= \int_0^\tau M(s,\tau)(\omega) h'(s) ds \int_0^\tau h'(u) \int_{sup(u,s)}^\tau b''(\omega_\alpha) M(u,\alpha) d\alpha du \qquad (4.20)$$

where, at the second step, we have replaced  $\beta(\alpha)$  by its expression (2.1). We have to evaluate the sum

$$J = \sum_{k \ge 0} e'_k(s) \int_0^1 e'_k(v) g_s(v) dv$$
 (4.21)

where

$$g_{s}(v) = \int_{sup(s,v)}^{\tau} M(v,\alpha) b''(\omega_{\alpha}) d\alpha \qquad (4.22)$$

J is the sum of the Fourier series of g at the point v = s. We deduce (4.18).

**Proposition 4.6.** Let A be the Laplacian (3.1). The first order term in (4.2) is given by

$$A(x^{i}(\tau))(I^{-1}\omega)\frac{\partial\psi}{\partial x_{i}}(\omega_{\tau})$$
(4.23)

proof. We do the proof when n = 1. We calculate

$$\sum_{k} D_{e_{k}}^{2} x(\tau)(\omega) \tag{4.24}$$

We have

$$D_h x(\tau)(\omega) = \int_0^\tau exp[\int_s^\tau b'(x_u(\omega))du]h'(s)ds$$

and

$$D_h^2 x(\tau)(\omega) = \frac{d}{d\varepsilon} \sum_{|\varepsilon=0} D_h x(\tau)(\omega + \varepsilon h)$$

$$=\int_0^\tau ds \qquad M(s,\tau)(I\omega)h'(s)\int_s^\tau du \qquad b''(x_u(\omega))\int_0^\tau d\gamma \qquad M(\gamma,u)(I\omega)h'(\gamma) \ (4.25)$$

After changing the order of integration in (4.25), we calculate the sum (4.24) as the sum of a Fourier series. We obtain that the sum (4.24) is equal to

$$\int_0^{\tau} M(s,\tau)(I\omega) \int_s^{\tau} M(s,u)(I\omega)b''(x_u(\omega))duds \qquad (4.26)$$

We compare with (4.18) and it yields (4.23).

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